



RF Trip Compensation for Beam Stability

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RF&Linac Section - ALBA Accelerators Division

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- ✓ Introduction and Motivation
 - SR RF Plants
 - ALBA LLRF
 - RF Operation
- ✓ Feed-Forward Loops for RF Trip Compensation
 - Amplitude Modulation
 - Phase Modulation
 - Phase Step Modulation
- ✓ Future Upgrade: Feedforward for Beam Loading Compensation
- ✓ Conclusions

Introduction and Motivation

RF Parameters

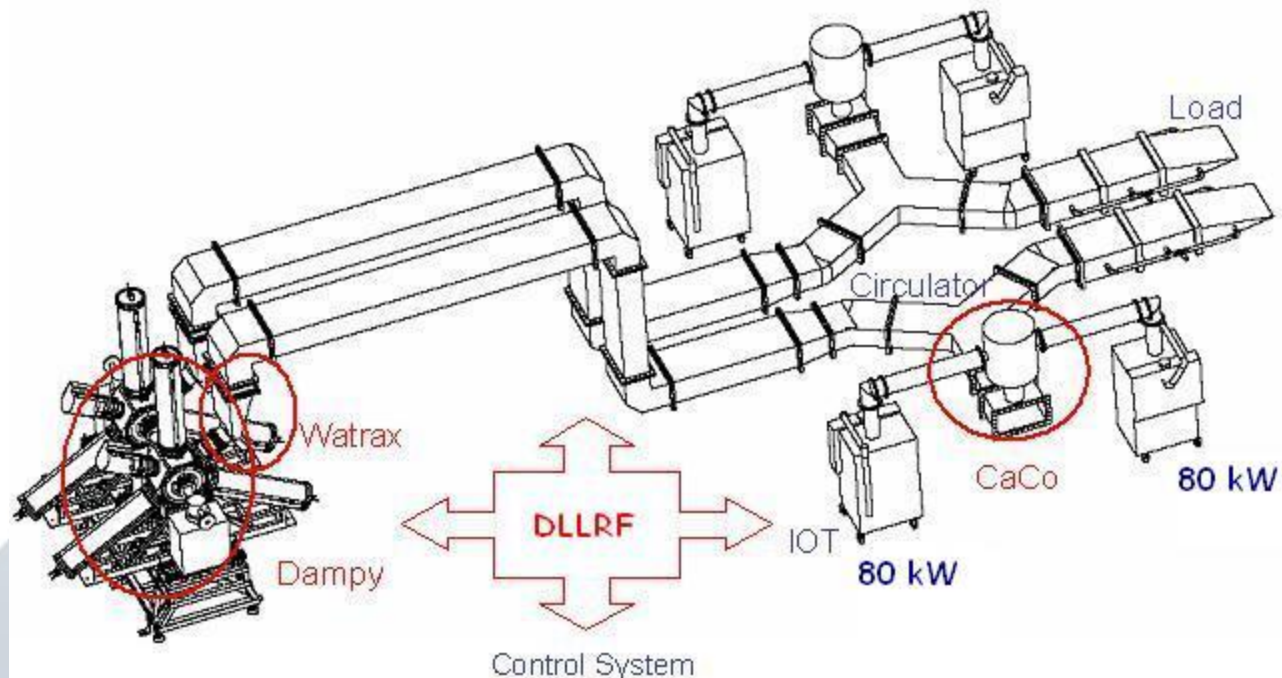
U_0 1.3MeV/turn

V_{total} 3.6 MV

q ≈ 2.5

f_s ≈ 9 kHz

P_{RF} 960kW



6 RF Plants of 160kW at 500 MHz

2 IOT Transmitters per RF cavity. Power combined in CaCo

Dampy Cavity

Normal Conducting

Single cell, HOM damped

3.3 M Ω

Digital LLRF System based on IQ mod/demod

Main Characteristics

- ✓ Based on digital technology using a commercial cPCI board with FPGA
- ✓ Signal processing based on IQ demodulation technique
- ✓ Main loops: Amplitude, phase and tuning
- ✓ RF diagnostics: Circular buffer for post-mortem analysis (0.5s)
- ✓ Extra utilities
 - Automatic conditioning for cavities
 - Automatic cavities recovery



Digital board: VHS-ADC from Lyrtech

Loops Resolution and bandwidth (adjustable parameters)

	Resolution	Bandwidth	Dynamic Range
Amplitude Loop	< 0.1% rms	[0.1, 50] kHz	30dB
Phase Loop	< 0.1° rms	[0.1, 50] kHz	360°
Tuning	< ± 0.5°	--	< ± 75°

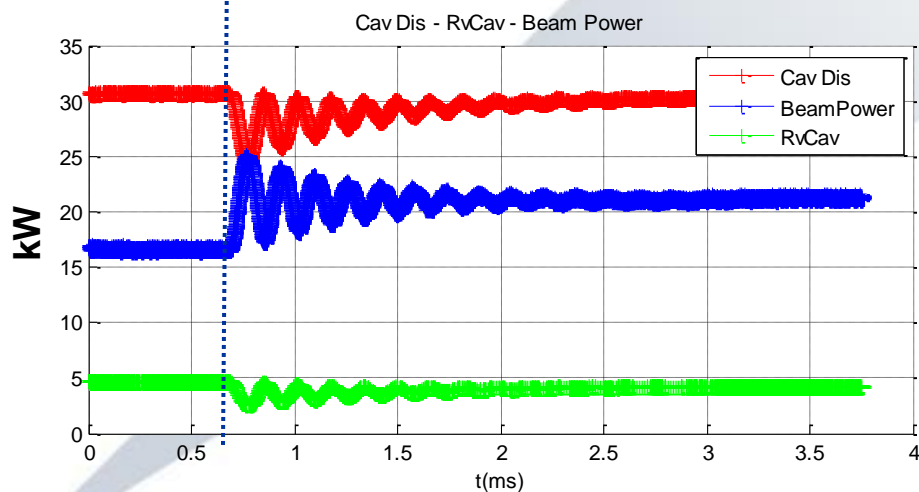
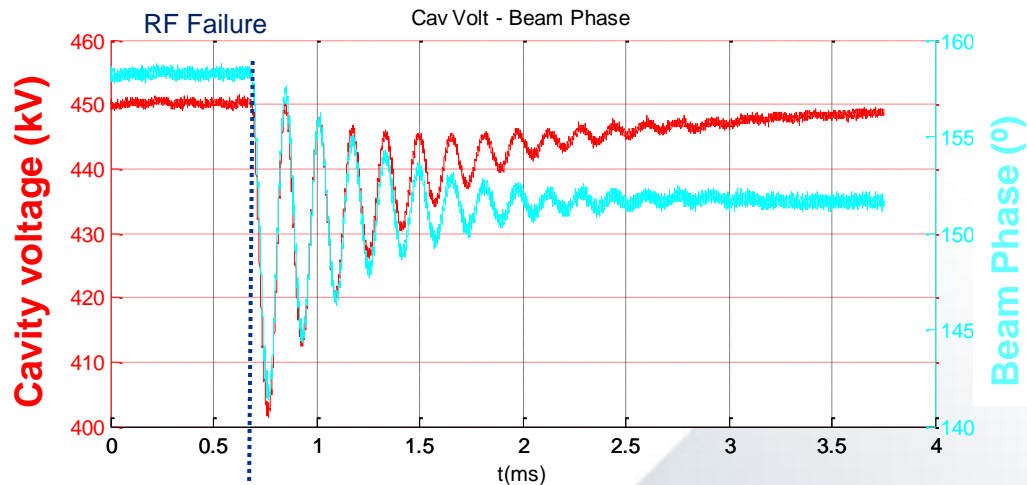
At present

- ✓ Running at 110mA with 2.6MV of RF Voltage in SR
- ✓ 2 or 3 RF Interlocks per week
- ✓ One RF Trip does not cause beam loss (enough over-voltage)
- ✓ Automatic recovery allows setting into operation a tripped plant with circulating beam

In Future

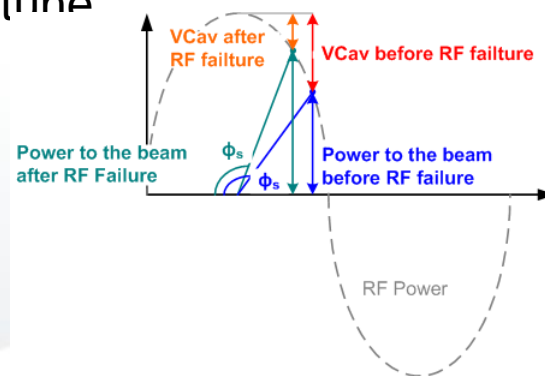
- ✓ SR Current will be increased up to nominal current 250mA (SR RF designed to withstand 400mA)
- ✓ With present available RF voltage, higher SR currents will lead to beam losses when an RF plant trips
- ✓ Solution: Active compensation of RF Trip disturbances

Active RF Trip Compensation

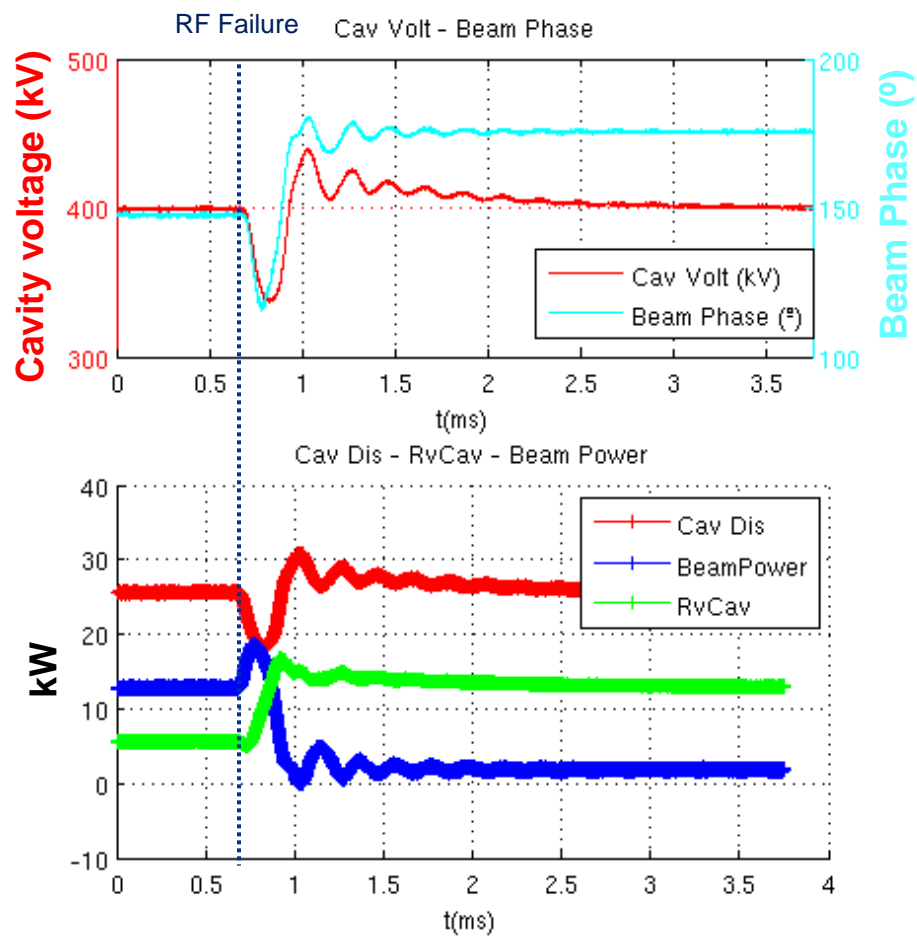


**Response of active cavities
after RF Trip**

- **Cavity voltage and synchronous phase drop and they start to oscillate with a frequency equal to synchrotron time**



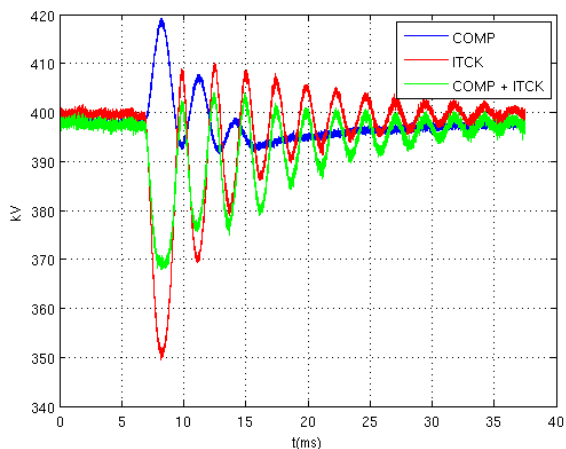
- **Beam extracts more power from cavity**
- **Reverse power of the cavity decreases**
- Amplitude of oscillations depend on beam current
- Frequency oscillations depend on how much RF voltage is left



- Cavity voltage decreases and then there is **an overshoot**
- Synchronous phase decreases
- But, reverse power increases and power delivered to the beam decreases → **Power extracted from the beam** → **Partial beam lost**
- So, if behavior known, compensation can be applied before losing the beam

Response of active cavities after RF Trip

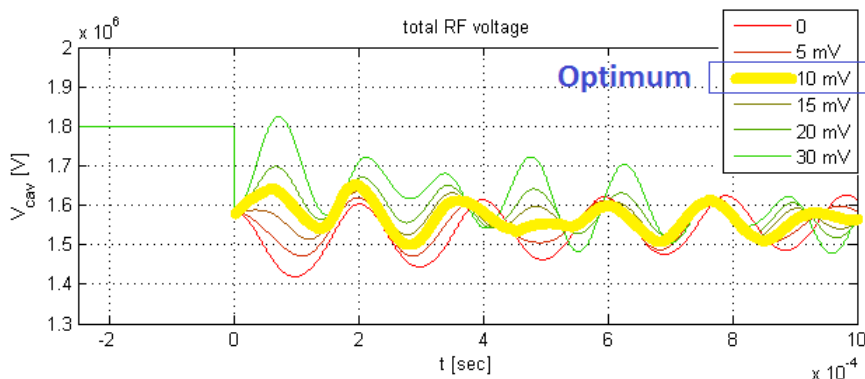
✓ Active compensation of disturbance: **Theoretical results**



Response of 06A Cavity Voltage after stopping
Cavity 10B – 60mA

- Cavity Voltage oscillations after interlock measured
- Compensation activated for first periods (Amplitude modulation with frequency equal to synchrotron tune)
- Overlap of two responses
- Sum of two responses: theoretical result
 - Decrease of perturbations by a half

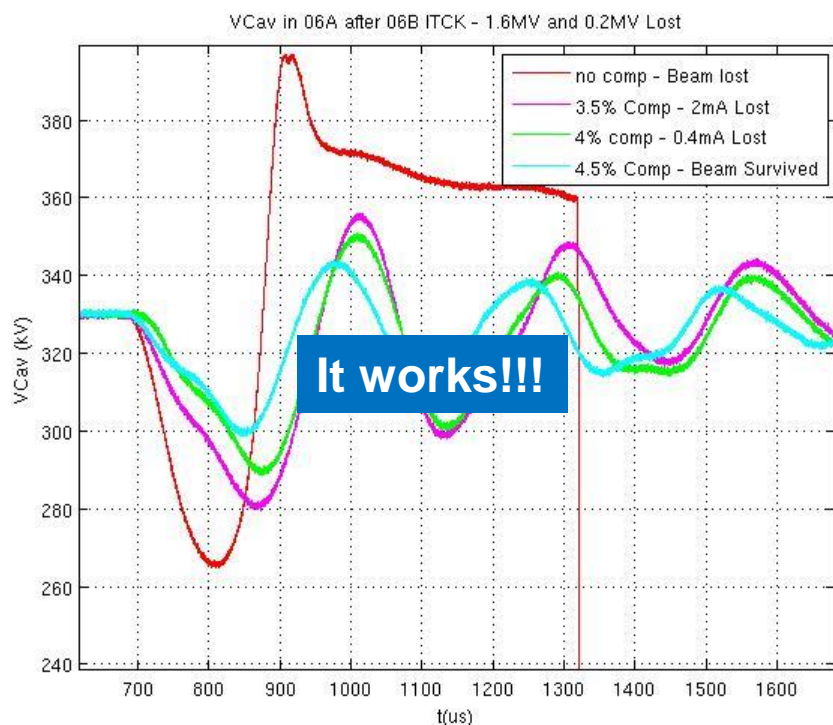
✓ Simulations done by J. Marcos to calculate optimum compensation



- Analysis of Overall Cavity Voltage after trip applying compensation with different amplitudes
- **Optimum:** Compensation where no voltage overshoots were observed

✓ Initial conditions:

- 5 Active Cavities
- Total RF Voltage = 1.6MV (320kV per cavity)
- Ibeam = 60mA
- Fake Interlock created in one cavity



Voltage of Active Cavity after RF Trip

✓ Analysis of Cavity Voltage of 06A after trip in 06B with amplitude compensations

- With no compensation: Beam lost
- With 3.5% compensation – 2mA lost
- With 4.0% compensation – 0.5mA lost
- With 4.5% compensation – Beam survived

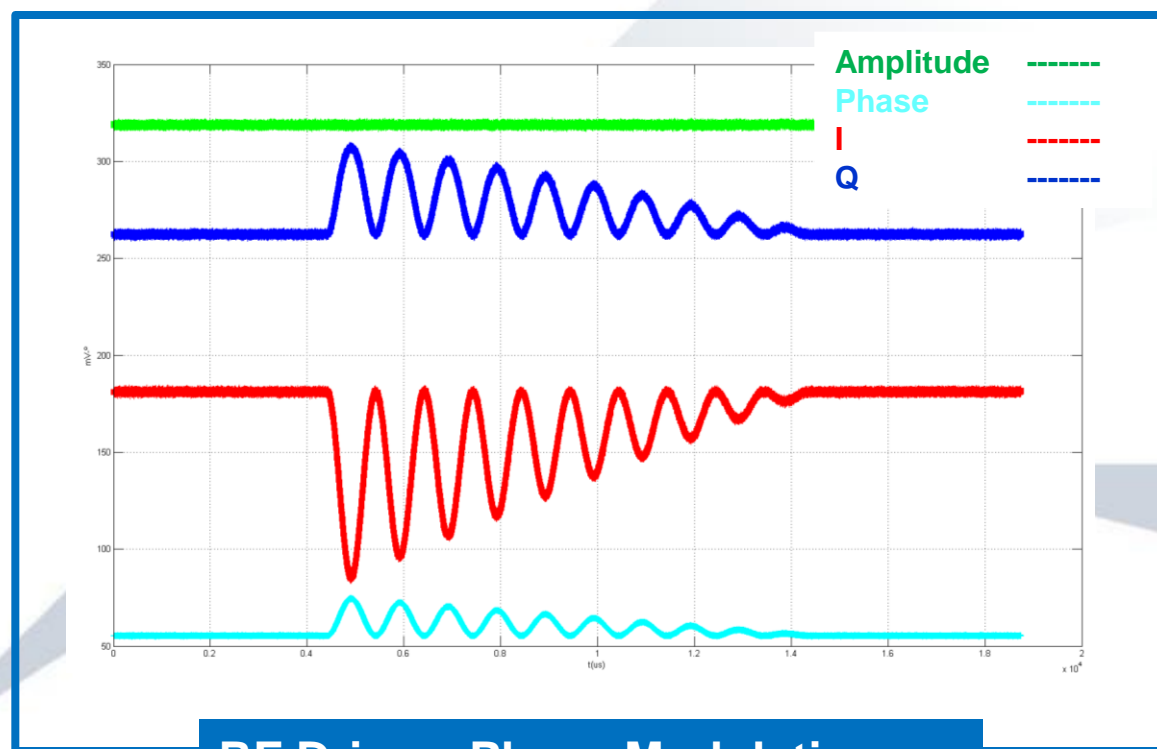
✓ Still 4.5% overdrive (1dB) could be high when working at higher current/power

✓ Other compensation strategies analyzed

- phase modulation to compensate oscillations instead of amplitude modulation
- No overdrive needed

✓ Frequency Phase Modulation

- Amplitude of RF Drive kept constant
- Phase of RF Drive modulated to compensate longitudinal oscillations of beam
- Frequency equal to synchrotron tune
- Tested with beam, but not conclusive results. Further tests needed

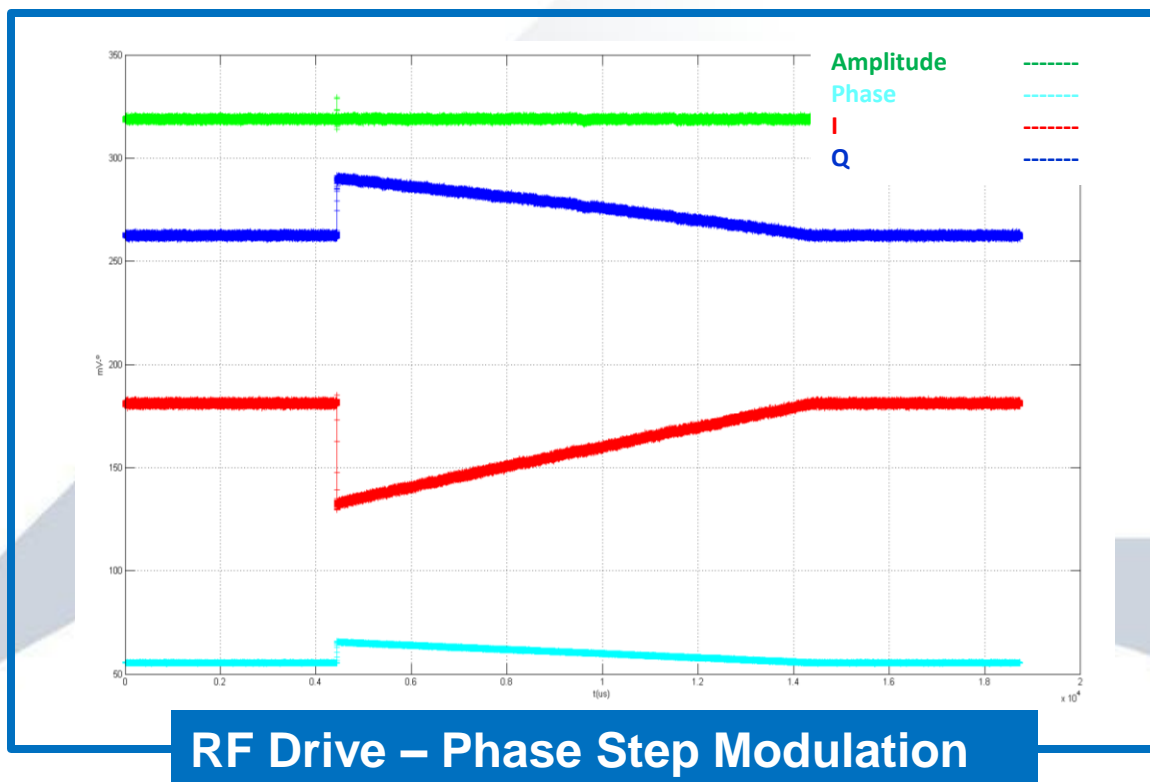


Example of Frequency Phase Modulation

- Modulation Freq = 10kHz
- Phase Mod = 10^0
- Decay time = 10ms

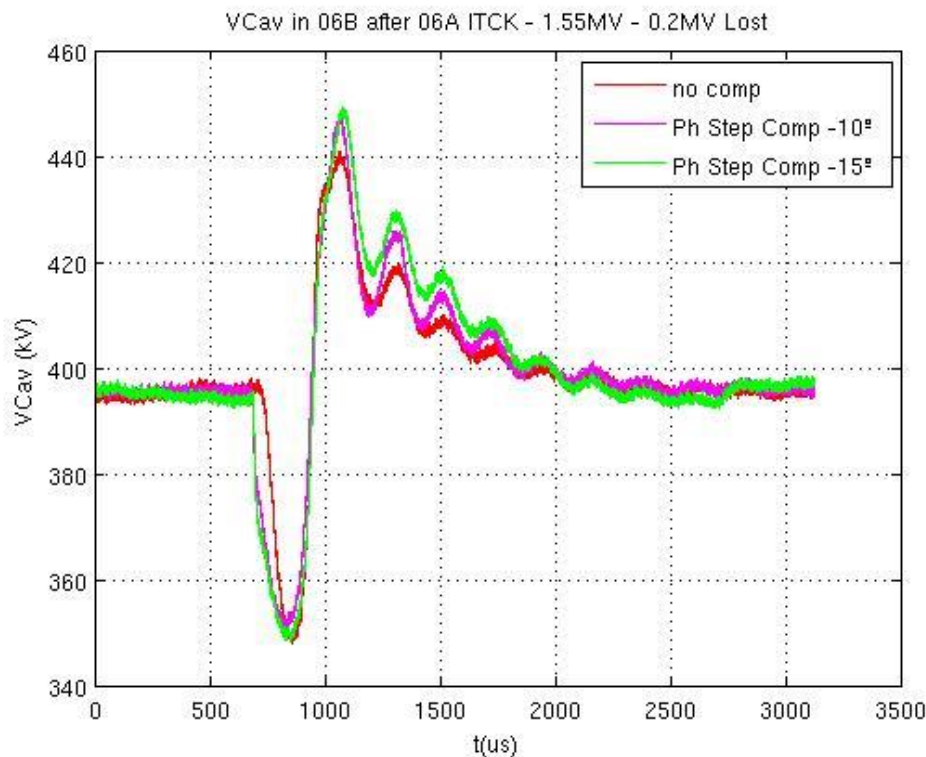
✓ Phase Step Modulation

- Phase of RF Drive changed $\Delta\phi$ with a step which decreases with a decay time equal to damping time
- Capable to compensate partial beam loss, but not total beam loss



✓ Initial conditions:

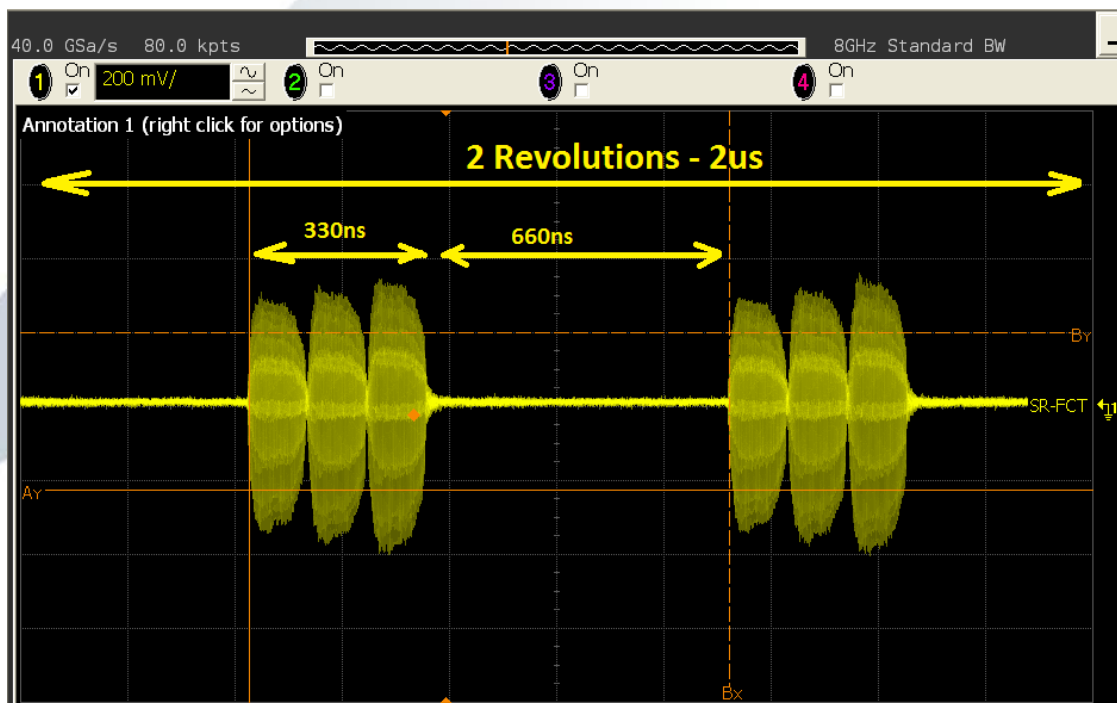
- 5 Active Cavities
- Total RF Voltage = 1.55MV (3x450kV + 1x200kV)
- Ibeam = 60mA
- Fake Interlock created in 200kV Cavity



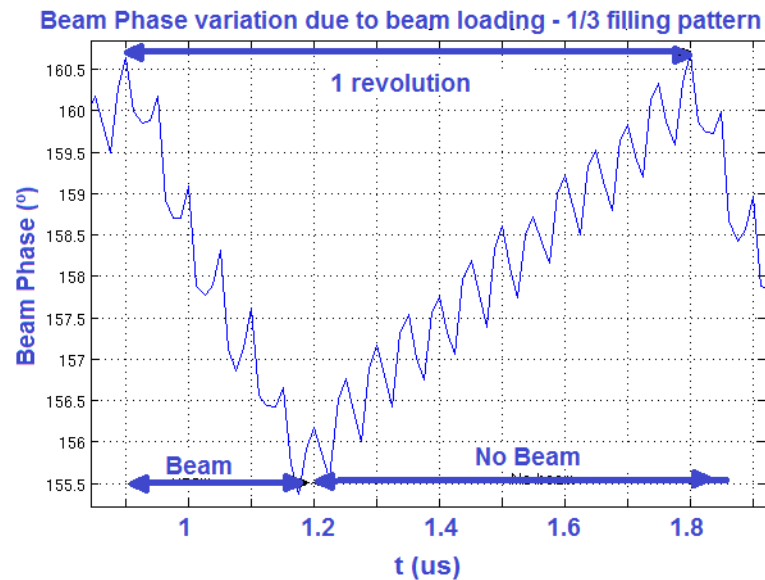
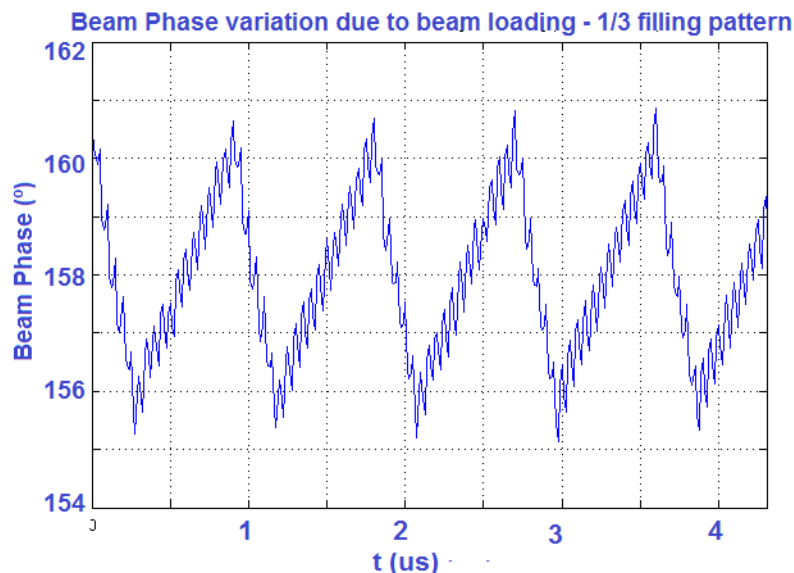
✓ Analysis of Cavity Voltage of 06B after trip in 06A with phase step compensation

- Beam loss partially compensated, but no conclusive results
- Further tests needed

- ✓ **In Normal Operation: Effect of beam loading negligible**
 - *Revolution frequency $\sim 1\text{MHz}$*
 - *90% Filling Pattern*
 - *10 trains: 10 x (32 bunches + 12 empty buckets)*
- ✓ **Filling pattern modified to 1/3 to be able to measure beam loading effect**



✓ Beam Loading measured with 1/3 filling pattern (60mA)



- *Beam Phase modified by 5° due to beam loading effect*
- *Future upgrade: Phase modulation (feed-forward loop) to compensate this effect*
- *Needed to prove feasibility of this approach for CLIC collaboration*

✓ RF Operation:

- 2 or 3 RF interlocks per week
- Beam survives after RF Trip with present configuration: 110mA – 2.6MV RF voltage

✓ RF Trip Compensation:

- Amplitude Modulation can compensate beam loss due to RF Trip, but overdrive needed (higher stress to IOT)
- Other RF Trip compensation approaches being studied (phase modulation and phase step modulation)
- RF Trip compensation would allow increasing SR Current keeping RF Voltage and keeping beam availability when an RF Trip occurs

✓ Feed-Forward loops for beam loading compensation being studied

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Thanks for your attention
Questions?